

Problems 7

6 November, 2020

Vectors

1. Express vector v as a linear combination of vectors a, b, \dots for following values of v, a, \dots :

$$(\alpha) \quad v = [2, 3], a = [1, -1], b = [1, 1]$$

$$(\beta) \quad v = [1, 1], a = [1, -1], b = [0, 1]$$

$$(\gamma) \quad v = [1, 1, 1]$$

$$a = [1, -1, 0], b = [1, 1, -2], c = [3, 2, 1]$$

$$(\text{harder}) \quad v = \cos^2(x), a = \sin(2x), b = \cos(2x), c = 1$$

2. Find Euclidean length of following vectors

$$(\alpha) \quad [1, 1, 1]$$

$$(\beta) \quad [0, 0, 1]$$

$$(\gamma) \quad [\sin(x), \cos(x), 0]$$

$$(\delta) \quad [\sin(x), \cos(x) \sin(y), \cos(x) \cos(y)]$$

3. Let $f(a, b, c) = (a \times b) \cdot c$ for $a, b, c \in \mathbb{R}^3$ show that:

$$(\alpha) \quad f(a, b, c) = f(c, a, b) = f(b, c, a)$$

$$(\beta) \quad f(a, b, c) = -f(a, c, b)$$

deduce that $f(a, b, a) = 0$.

4. Find orthogonal basis for \mathbb{R}^3 that contains vector $[1, 1, 1]$.

Matrices

1. By considering action on standard basis of \mathbb{R}^3 find matrix representation of following linear transformations:

(α) Reflection in xy plane.

(β) 90° rotation around x axis.

(γ) Reflection in xy plane followed by 90° rotation around x axis.

(δ) 90° rotation around x axis followed by reflection in xy plane

2. In basis $b_1 = [1, 1]^T, b_2 = [1, -1]^T$ matrix M has representation $\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$. Write this matrix representation in standard basis.

3. Find determinant of following matrices

$$(\alpha) \quad \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$(\beta) \quad \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$(\gamma) \quad \begin{bmatrix} \sin(x) & \cos(x) \\ -\cos(x) & \sin(x) \end{bmatrix}$$

$$(\delta) \quad \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$(\varepsilon) \quad \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$(\zeta) \quad \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 4 & 9 & 16 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$(\eta) \quad \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & a & b \\ 0 & 0 & c & d \end{bmatrix}$$

$$(\theta) \quad \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

(harder) $N \times N$ matrix with all entries equal to 1 (hint: eigenvalues).

Eigenvectors and eigenvalues

1. A symmetric matrix is called positive-definite if all its eigenvalues are positive. Which of the following are positive definite:

$$(\alpha) \begin{bmatrix} 5 & 1 \\ 1 & 5 \end{bmatrix}$$

$$(\beta) \begin{bmatrix} 1 & 5 \\ 5 & 1 \end{bmatrix}$$

$$(\gamma) \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

$$(\delta) \begin{bmatrix} -1 & 9 \\ 9 & -1 \end{bmatrix}$$

2. Find values of real parameter q for which the following are positive definite:

$$(\alpha) \begin{bmatrix} 1 & 1 \\ 1 & q \end{bmatrix}$$

$$(\beta) \begin{bmatrix} q & 1 \\ 1 & q \end{bmatrix}$$

$$(\gamma) \begin{bmatrix} q & 1 \\ 1 & q^{-1} \end{bmatrix}$$

$$(\delta) \begin{bmatrix} 1 & q \\ q & 1 \end{bmatrix}$$

3. (harder) Show that any eigenvalue of real symmetric matrix is real.

Physics

1. Compute inertia tensor of a rigid tetrahedron made of massless rods and equal point masses at each vertex.